



Distributed Termination Detection

Alexandre David

1.2.05

adavid@cs.aau.dk



Termination Detection: The Model

- A process is either **active** or **inactive**.
- An inactive process may not send messages.
- An active process may turn inactive.
- An inactive process stays inactive unless it receives a message.
- Find out when we can terminate.

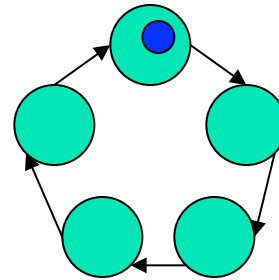


What is the Problem?

- A message can turn an inactive process active.
 - You don't know if an inactive process will be turned active later...
- Find out whether all processes are inactive **and** whether there are no more messages in the system.
 - And avoid races, like message sent not yet received...

Simple Token Algorithm

Processes arranged in a ring.



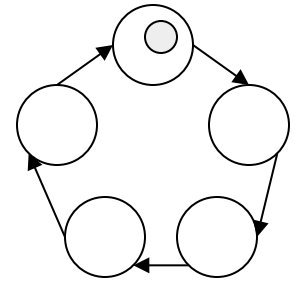
Process 1 inserts a token that will travel around back to 1.
The token leaves a process only if it's inactive.
Process 1 determines when to terminate.

That does not work here:

- A process may become active **after** having sent the token.
- Who sent that message?
- Fix this: Dijkstra.

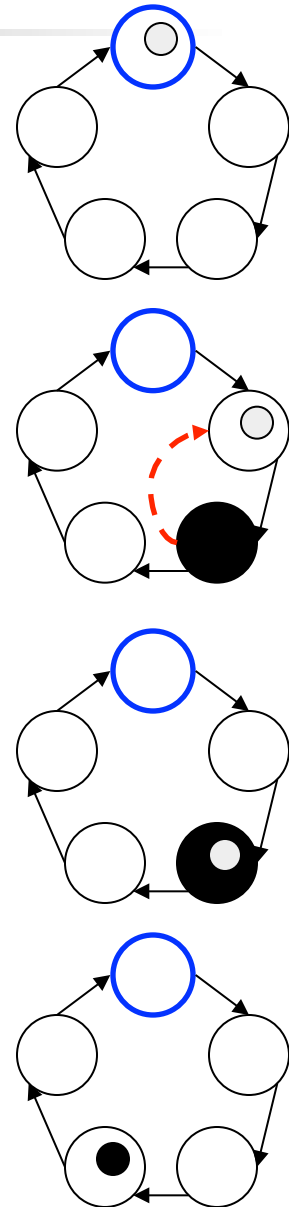
Dijkstra's Token Termination Detection Algorithm - Idea

- All processes are initially colored white.
- A process i sending a message to process j with $j < i$ is a suspect for reactivating a process \Rightarrow It turns black.
- If a black process receives a token, it colors it black.



Dijkstra's Token Termination Detection Algorithm

- 1) When P_1 turns inactive, it turns white and sends a white token to P_2 .
- 2) If P_i sends a message to P_j and $j < i$ then P_i turns black.
- 3) If P_i has the token and is idle, it passes the token. The token becomes black if P_i is black.
- 4) After passing tokens, processes become white.
- 5) The algorithm terminates when P_1 receives a white token and it is idle.





Cost

- The token consumes $O(P)$ in time.
 - P_1 may become active again before getting back the token.
 - For a small number of processes, algorithm is acceptable.
 - For large numbers of processes, this becomes a significant overhead.
 - So far so good?





What Can Go Wrong Will Go Wrong

- What happens if P_i sends a message to P_j , $j > i$?
 - P_i may be white when it receives a white token later and forwards a white token. *Token faster than the message - race.*
 - Messages must be delivered **in order** for the protocol to work!
- MPI guarantees that messages are **non-overtaking**: M_1 sent before M_2 from **the same** source will arrive before M_2 at **the same** destination.
 - But no in-order guarantee!
 - Not good enough!



Dijkstra-Scholten Algorithm

- 1) Every process keeps a message count.
 - 1) Increment the count for received messages.
 - 2) Decrement the count for sent messages.
- 2) P_1 is the initiator and sends a white token with a count=0.
- 3) If P_i sends or receive messages, it turns black.
- 4) If P_i receives the token,
 - 1) it keeps it while it is active,
 - 2) if it is black, the token becomes black,
 - 3) when it is inactive, it forwards the token with its message count added and turns white.
- 5) If P_1 is white, it receives a white token, and the message count+its count == 0, then P_1 has detected termination.



Getting Back the Results

- When P_1 has detected termination, it can act as a master and
 - send a terminate message to everyone,
 - collect the results and print them,
 - Collecting the results could be done in parallel too!
 - send a shutdown message to everyone,
 - stop.