Principle of Parallel Algorithm Design

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Today

- Preliminaries (3.1).
- Decomposition Techniques (3.2).
- Surprise.

Overview

- Introduction to parallel algorithms.
 - Tasks and decomposition.
 - Processes and mapping.
 - Processes vs. processors.
- Decomposition techniques.
 - Recursive decomposition.
 - Exploratory decomposition.
 - Hybrid decomposition.

Introduction

- Parallel algorithms have the added dimension of *concurrency*.
- Typical tasks:
 - Identify concurrent works.
 - Map them to processors.
 - Distribute inputs, outputs, and other data.
 - Manage shared resources.
 - Synchronize the processors.

Decomposing Problems

- Decomposition into *concurrent* tasks.
 - No unique solution.
 - Different sizes.
 - Decomposition illustrated as a directed graph:
 - Nodes = tasks.
 - Edges = dependency.

Task dependency graph



Example: Database Query Processing

MODEL = ``CIVIC'' AND YEAR = 2001 AND (COLOR = ``GREEN'' OR COLOR = ``WHITE)

ID#	Model	Year	Color	Dealer	Price
4523	Civic	2002	Blue	MN	\$18,000
3476	Corolla	1999	White	IL	\$15,000
7623	Camry	2001	Green	NY	\$21,000
9834	Prius	2001	Green	CA	\$18,000
6734	Civic	2001	White	OR	\$17,000
5342	Altima	2001	Green	FL	\$19,000
3845	Maxima	2001	Blue	NY	\$22,000
8354	Accord	2000	Green	VT	\$18,000
4395	Civic	2001	Red	CA	\$17,000
7352	Civic	2002	Red	WA	\$18,000

Table 3.1 A database storing information about used vehicles.

A Solution



Figure 3.2 The different tables and their dependencies in a query processing operation.

Another Solution



Granularity

- Number and size of tasks.
 - Fine-grained: many small tasks.
 - Coarse-grained: few large tasks.
- Related: *degree of concurrency*.
 - Maximal degree of concurrency.
 - Average degree of concurrency.

Coarser Matrix * Vector



Granularity

- Average degree of concurrency if we take into account varying *amount of work?*
- Critical path = longest directed path between any start & finish nodes.
- Critical path length = sum of the weights of nodes along this path.
- Average degree of concurrency = total amount of work / critical path length.

Database Example

Critical path (3). Critical path length = 27. Av. deg. of concurrency = 63/27.

Critical path (4). Critical path length = 34. Av. deg. of conc. = 64/34.



Interaction Between Tasks

- Tasks often share data.
- Task interaction graph:
 - Nodes = tasks.
 - Edges = interaction.
 - Optional weights.
- Task dependency graph is a sub-graph of the task interaction graph.

Example: Sparse Matrix Multiplication



Figure 3.6 A decomposition for sparse matrix-vector multiplication and the corresponding taskinteraction graph. In the decomposition Task *i* computes $\sum_{0 \le j \le 11, A[i,j] \ne 0} A[i, j] \cdot b[j]$.

Processes and Mapping

- Tasks run on processors.
- Process: processing agent executing the tasks. Not exactly like in your OS course.
- Mapping = assignment of tasks to processes.
- API expose processes and binding to processors not always controlled.

Mapping Example



Figure 3.7 Mappings of the task graphs of Figure 3.5 onto four processes.

Processes vs. Processors

- Processes = logical computing agent.
- Processor = hardware computational unit.
- In general 1-1 correspondence but this model gives better abstraction.
- Useful for hardware supporting multiple programming paradigms.

Now remains the question: How do you decompose?

Decomposition Techniques

- Recursive decomposition.
 - Divide-and-conquer.
- Data decomposition.
 - Large data structure.
- Exploratory decomposition.
 - Search algorithms.
- Speculative decomposition.
 - Dependent choices in computations.

Recursive Decomposition

- Problem solvable by divide-and-conquer:
 - Decompose into sub-problems.
 - Do it recursively.
 - Combine the sub-solutions.
 - Do it recursively.
- Concurrency: The sub-problems are solved in parallel.

Quicksort Example



Figure 3.8 The quicksort task-dependency graph based on recursive decomposition for sorting a sequence of 12 numbers.



Figure 3.9 The task-dependency graph for finding the minimum number in the sequence {4, 9, 1, 7, 8, 11, 2, 12}. Each node in the tree represents the task of finding the minimum of a pair of numbers.

Data Decomposition

- 2 steps:
 - Partition the data.
 - Induce partition into tasks.
- How to partition data?
- Partition output data:
 - Independent "sub-outputs".
- Partition input data:
 - Local computations, followed by combination.

Matrix Multiplication

$$\begin{pmatrix} A_{1,1} & A_{1,2} \\ A_{2,1} & A_{2,2} \end{pmatrix} \cdot \begin{pmatrix} B_{1,1} & B_{1,2} \\ B_{2,1} & B_{2,2} \end{pmatrix} \rightarrow \begin{pmatrix} C_{1,1} & C_{1,2} \\ C_{2,1} & C_{2,2} \end{pmatrix}$$
(a)
Task 1: $C_{1,1} = A_{1,1}B_{1,1} + A_{1,2}B_{2,1}$
Task 2: $C_{1,2} = A_{1,1}B_{1,2} + A_{1,2}B_{2,2}$
Task 3: $C_{2,1} = A_{2,1}B_{1,1} + A_{2,2}B_{2,1}$
Task 4: $C_{2,2} = A_{2,1}B_{1,2} + A_{2,2}B_{2,2}$
(b)

Figure 3.10 (a) Partitioning of input and output matrices into 2×2 submatrices. (b) A decomposition of matrix multiplication into four tasks based on the partitioning of the matrices in (a).

Intermediate Data Partitioning



Linear combination of the intermediate results.

Owner Compute Rule

- Process assigned to some data
 - is responsible for all computations associated with it.
- Input data decomposition:
 - All computations done on the (partitioned) input data are done by the process.
- Output data decomposition:
 - All computations for the (partitioned) output data are done by the process.

Exploratory Decomposition

15-puzzle example



Figure 3.17 A 15-puzzle problem instance showing the initial configuration (a), the final configuration (d), and a sequence of moves leading from the initial to the final configuration.







Figure 3.19 An illustration of anomalous speedups resulting from exploratory decomposition.

Speculative Decomposition

- Dependencies between tasks are not known a-priori.
 - How to identify independent tasks?
 - Conservative approach: identify tasks that are guaranteed to be independent.
 - Optimistic approach: schedule tasks even if we are not sure – may roll-back later.

Speculative Decomposition Example



Figure 3.20 A simple network for discrete event simulation.