Communication Costs in Parallel Machines

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- Communication Costs in Parallel Machines (2.5)
 - MPI
 - Shared Address Space
- Routing Mechanisms for Interconnection Networks (2.6)

Communication Costs in Parallel Machines

- Sources of overhead in parallel programs:
 - Idling.
 - Contention.
 - Communication costs.
- Costs depend on
 - Programming model.
 - Network topology.
 - Routing...

Message Passing Costs

- Total time for communication =
 - Startup time (t_s) only once per message
 - + Per-hop time (t_h) between directly connected nodes
 - + Per-word transfer time (t_w) 1/bandwidth.



Store-and-Forward Routing

- Intermediate nodes
 - store the whole message.
 - forward the whole message.
- Message size m traversing / links:
 - $t_{com} = t_s + (m^*t_w + t_h)^*/$
 - Pay $m*t_w$ for every link.
 - In practice $t_{com} = t_s + m*t_w*I$

Packet Routing

- Cut the message in smaller parts.
- Advantages:
 - Lower overhead for errors (less retransmission).
 - More robust routing (different paths for packets, avoid congestion).
 - Better error correction.
 - Better resource utilization (like pipeline).
 - But... more complex protocol.

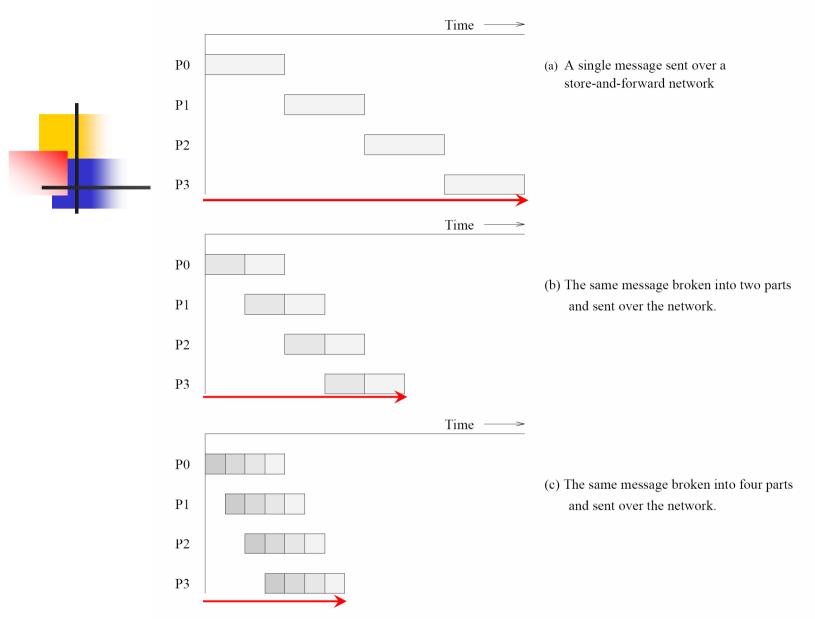


Figure 2.26 Passing a message from node P_0 to P_3 (a) through a store-and-forward communication network; (b) and (c) extending the concept to cut-through routing. The shaded regions represent the time that the message is in transit. The startup time associated with this message transfer is assumed to be zero.

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Packet Routing

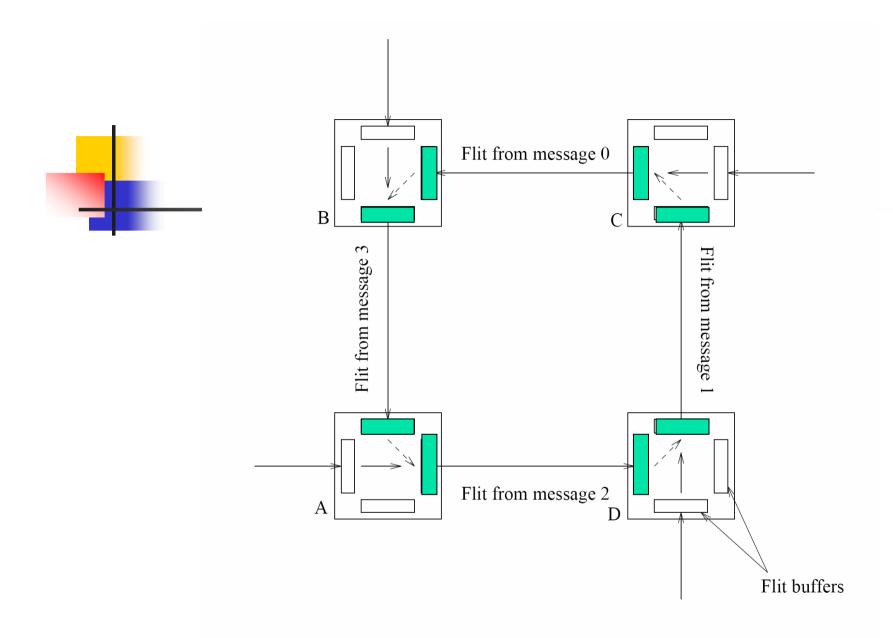
Message size m traversing / links:

•
$$t_{com} = t_s + t_h */ + t_w *m$$

• with $t_w = t_{w1} + t_{w2}(1+s/r)$
packing overhead

Cut-Through Routing

- Simplified packet routing:
 - Packets take the same path (1x routing information).
 - In sequence packet delivery (no sequencing).
 - Error detection at message level, cheap detection (for good networks).
 - Fixed size unit for packets = flow control digits (flits).
 - Same cost model with smaller s.



---> Desired direction of message traversal

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Figure 2.27 An example of deadlock in a cut-through routing network.

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Simplified Cost Model

- $t_{com} = t_s + t_h * / + t_w * m$
- Optimize:
 - Communicate in bulk (fewer t_s).
 - Minimize volume (smaller m).
 - Minimize number of hops (smaller /), but difficult.
- Almost same time between any pair = like a completely connected network.

Costs in Shared Address Space Machines

- Difficult to have accurate models because:
 - Memory layout depends on the system.
 - Limitations with caches.
 - Invalidate/update overheads difficult to estimate (cache coherence protocols).
 - Spatial locality difficult to estimate.
 - Prefetching plays its role.
 - False sharing may be a problem.
 - Contention...

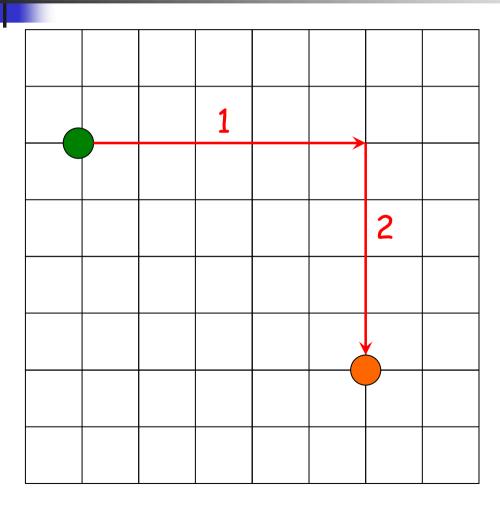
Routing Mechanisms for Interconnection Networks

- Goal: find a path from src to dest.
- Types:
 - Minimal: selects shortest path, progress at every hop – prone to congestion
 - vs. non-minimal: may use longer path to avoid congestion.
 - Deterministic: finds a unique path
 - vs. adaptive: use current state to find a path.

Good Routing

- Prevents deadlock.
 - Use dimension ordered routing.
 - XY-routing for 2-D mesh.
 - E-cube routing for hypercubes.
- Avoids hot-spots.
 - Two-step routing may be used.





Path length = |Sx - Dx| + |Sy - Dy|

E-Cube Routing

- N-dimension hypercube:
 - Nodes have N neighbors.
 - 2^N nodes.
 - Numbering scheme s.t. change 1 bit along any dimension.
- Routing: progress towards a goal number.

E-Cube Routing

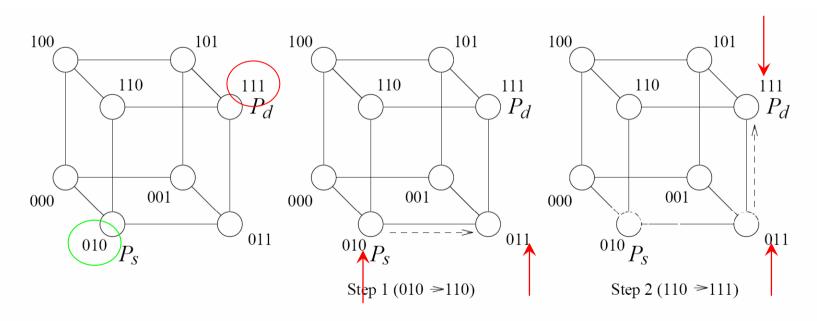


Figure 2.28 Routing a message from node P_s (010) to node P_d (111) in a three-dimensional hypercube using E-cube routing.